

## **Referenze:**

[1] Combining Temporal Planning with Probabilistic Reasoning for Autonomous Surveillance Missions

Sara Bernardini, Maria Fox and Derek Long

Autonomous Robots (AURO) (5-year impact factor: 4.095) , Vol. 41, No. 1, 01.2017, p. 181-203, Springer.

[2] Goal recognition design.

Sarah Keren, Avigdor Gal, and Erez Karpas.

In Proceedings of the 24th International Conference on Automated Planning and Scheduling (ICAPS), June 2014.